PROGRAMAÇÃO MATLAB

<https://www.mathworks.com/videos/programming-an-arduino-robot-in-simulink-123449.html>

<https://www.mathworks.com/discovery/robot-programming.html>

<https://www.mathworks.com/videos/learning-robotics-with-matlab-and-simulink-1576474706574.html>

<https://www.mathworks.com/help/robotics/ug/build-a-robot-step-by-step.html>

<https://www.mathworks.com/help/reinforcement-learning/ug/quadruped-robot-locomotion-using-ddpg-gent.html>

<https://www.mathworks.com/matlabcentral/fileexchange/64237-running-robot-model-in-simscape> (já dei download)

<https://www.mathworks.com/help/reinforcement-learning/ug/quadruped-robot-locomotion-using-ddpg-gent.html>

<https://www.mathworks.com/videos/programming-robots-with-ros-and-ros2-using-matlab-and-simulink-1600976607866.html>

<https://www.mathworks.com/videos/model-based-control-of-humanoid-walking-1574399243682.html>

Tese

<https://recipp.ipp.pt/bitstream/10400.22/7168/1/DM_TomasCastro_2012_MEEC.pdf>

<https://www.researchgate.net/publication/330959700_Designing_and_Implementing_Trajectory_Planning_and_Inverse_Kinematics_Algorithms_using_Hexapod_Robot_Platform>

<file:///C:/Users/Guidinha/Downloads/2697-Article%20Text-4853-2-10-20220301.pdf>

O que o stor me mandou: Cinemática inversa

<file:///C:/Users/Guidinha/Desktop/UA/HP_4%20ano-2%20semestre/PSA/An_inverse_kinematic_algorithm_for_the_human_leg.pdf>

Model

<https://github.com/mathworks/Simscape-Robot-4Legs>

<https://github.com/ShuoYangRobotics/QuadrupedSim>